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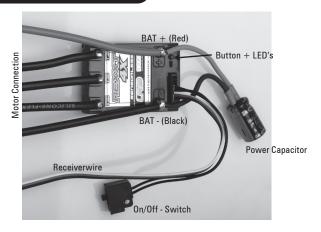
© LRP electronic GmbH 2008 BRUSHLESS SENSORLESS DESIGN MICRO CAR SPECIALIST

USER MANUAL



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1. CONNECTIONS



RX-/SWITCH HARNESS:

speed-control is equipped with the new RX-/Switch-Harness for maximum convienence. The regular LRP Multicon receiver wire is used and will easily fit in all ordinary receivers. Install the On/Off micro switch

POWER WIRES:

1.5 mm² power wires without any attached connectors are used. There are G3.5 gold connectors included which allow convienent installation with brushless motors such as the Vector Micro 370.

The unique solder posts allow easy and convenient replacement of the power wires. Nevertheless some soldering skills are required. Avoid soldering longer then 5 sec per soldering joint to prevent possible damage to the speed-control due to overheating of the components!

2. INSTALLATION

t 4X is supplied with 1.5mm² power-wires without attached connectors. There are G3.5 gold connected which allow convienent installation with brushless motors such as the Vector Micro 370. Be careful with the correct wire sequence/colors since an incorrect connection may damage the speed-control! Isolate all connections carefully.

Caution: Avoid soldering longer than 5sec per soldering joint when replacing the power wires on the speed-control and motor to prevent possible damage due to overheating of the components!

- Attach switch-/RX-wire harness to speedo (be careful with correct polarity)
- Connect the speed-control to the receiver (position: Channel 2)

- Motor A
- Brushless Motor
 Speedo MOT.A →
 Speedo MOT.B →
 Speedo MOT.C →

- Brushed Motor:

 Speedo MOT.A (blue) and MOT.B (yellow) will be the combined "minus" on brushed motor.

 Speedo MOT.C (orange) is the "plus" on bruhed
- Doublecheck all connections before connecting the speed-control to a battery. **CAUTION**: If battery is connected with reversed polarity it will destroy your speed-control!
- → Speedo "+" to battery "Plus"
 → Speedo "-" to battery "Minus"
- The speed-control is now ready to be set-up (see section 5).

3. USAGE TIPS

- Position the speed-control and capacitor where they are protected in the event of a crash and gives you easy access to the connectors and button.
- Make sure there is enough clearance between the speed-control, power-wires, antenna and receiver, Avoid any direct contact between power components, the receiver or the antenna as this can cause interference. If interference occurs, position the components at a different place in the model.
- Mount the speedo and capacitor using the supplied thick/black doubled-sided tape.
- The aerial should be run vertically up and away from the receiver. Avoid contact with any parts made of carbon fibre or metal. If the aerial is too long, don't coil up the excess length. See also the instructions supplied with your radio control system
- Because of the physical principles of brushless technology, the speed-controls do get a little hotter than brushed systems. Therefore it is required to let the speed-control cool down completely after every run.
- Sensorless brushless motors do not have a designated rotating direction and work identically in both directions. If the motor rotates the wrong way for your model, after you have wired up the three phase wires, then you can simply change motor rotation direction by swapping two of the three phase wires (e.g. SpeedoA goes to MotorB) and SpeedoB goes to MotorA)!



The crossed-out wheeled bin means that within the European Union the product must be taken to seperate collection at the product end-of-life. Do not dispose of these products as unsorted municipal waste.

thank you for your trust in this LRP product. By purchasing the LRP NEXXT 4X speed-control, you have chosen one of the most advanced sensorless brushless speed-controls of today. The Nexxt 4X, with all of its high-tech features and specially selected electronic components, is one of the best speed-controls currently available

- Brushless and Brushed Operation
- Micro Car Specialist
 8 ADPC™ Power Profiles
 Internal-Temp-Check System 2
 Multi-Protection System

- Sensorless Design
- Small size and lighweight
 AutoCell System (NiMH 4-9 / LiPo 2S + 3S)
 IceDrive Design

Please read the following instructions carefully before you start using your LRP Nexxt 4X speed control. This user guide contains important notes for the safety, the use and the maintenance of this product. Thus protecting yourself and avoid damages of the product.

Proceed according to the user guide in order to understand your *LRP Nexxt 4X* speed control better. Please take your time as you will have much more joy with your product if you know it exactly.

This user manual shall be kept in a safe place. If another customer is using this product, this manual has to be handed

4. SPECIFICATIONS

| Brushless + Brushed | yes | |
|---------------------------------|----------------|----------|
| Sensorless Brushless System | yes | |
| Forward / Brake | yes | |
| Forward / Brake / Reverse | yes | |
| Case Size | 28.5 x 40.3mm | |
| Weight (excl. wires) | 20g | |
| Voltage Input | 4.8 - 11.1V | |
| | BRUSHLESS | BRUSHED |
| Typ. Voltage Drop* @20A | 0.026V / phase | 0.019V |
| Rated Current* | 382A / phase | 382A |
| Rec. Motor Limit (370/380 size) | none | none |
| Rec. Motor Limit (540 size) | over 7.5 turns | over 13T |

| B.E.C. | 6.0V / 2.0A |
|--|--------------------|
| Internal-Temp-Check System 2 | yes |
| High Frequency | yes |
| Fail-Safe-System | yes |
| Multi-Protection-System | yes |
| Waterproof | yes |
| Integrated Solder Posts | yes |
| Power Wires | 1.5mm ² |
| 3.5mm Gold Connectors | included |
| 4 adjustable Modes (AutoCell, Motor/Drive-Settings, ADPC Powerprofiles, Autobrake) | yes |

Transistors rating at 25°C junction temperature

Specifications subject to change without notice

5. RADIO / SPEED-CONTROL SET-UP

In setup mode the Nexxt 4X stores radio calibrations after completed procedure, all the settings will be stored in the speed-controls memory even if the speed-control will be disconnected from the battery

TRANSMITTER SETTINGS

Setup the following basic functions on your transmitter (if available):

| Description | other names in radio | Required Setting |
|----------------------|----------------------|---|
| Throttle Travel | High ATV, EPA | 100% |
| Brake Travel | Low ATV, EPA, ATL | 100% |
| Throttle Exponential | EXP, EXPO | start with 0 |
| Neutral Trim | SUB Trim | centre |
| Servo Reverse | Throttle Reverse | any setting, don't change after set-up procedure! |

If your transmitter doesn't offer any of above functions, it's already in "basic setup" mode.

- Ensure that the speed-control is not connected to the drive battery and is switched off.
- Remove motor pinion or ensure that the wheels of the model are free to rotate
- . Switch the transmitter on and set the transmitter throttle stick to neutral
- · Connect the speed-control to the battery (switch in OFF position).
- Hold the button pressed and turn the switch on.
 → You entered setup mode and the blue LED flashes (it will flash until the setup is completed).
- Leave transmitter in neutral position and press the button once.
 Neutral setting is stored, yellow/blue LED flashes and the motor beeps.
- Hold full throttle on transmitter and press the button once
 Full-throttle setting is stored, red/blue LED flashes.
- Hold full brake on transmitter and press the button once.
 Brake setting is stored, red and blue LED's glow..
- This completes the setup procedure, stores all settings, and your Nexxt 4X is ready to use.
- If you make a mistake during the setup procedure, don't worry: Disconnect the battery for about 10 \sec and start again from the first step.
- At the end of each run switch off the car, and then switch off the transmitter.
- At the start of each run switch on the transmitter first, then switch on the car.
- For storage of the car, disconnect the drive battery at all times!

CHECKING THE FUNCTIONS:Check the LED's when moving your throttle stick and you will see if everything is setup correctly.

| FUNCTION | STATUS | Left LED | Right LED |
|------------------------------------|------------------|----------|-----------|
| Neutral (automatic brake inactive) | | off | blue |
| Neutral (automatic brake active) | | red | off |
| Forward | partial throttle | yellow | off |
| Forward | full throttle | yellow | blue |
| Brake | partial brake | red | off |
| Brake | full brake | red | blue |

6. SUPPRESSION





ONLY FOR BRUSHED MOTORS! Motors with no capacitors or not enough capacitors may interfe with the speed-control. To avoid this, solder t supplied capacitors to your motor (see picture).

7. MODE PROGRAMMING

The *Nexxt 4X* features 4 modes which enable you to adjust it to YOUR special requirements. The factory settings

are shown in grey colour.

This is the first LRP speed-control using a single button setup for radio-setup and mode adjustments, therefore it works in a slightly different way than known from LRP speed-controls before but we have retained the simple and intuitive logic from before to make it as user-friendly as possible

- How to get into "programming the modes"?
- How to know in which mode you are?

- · How to change the value?
- . How to get to the next mode?
- . How to leave the programming mode?
- → With speedo turned on, press button for 3sec until all 3 LED's flicker twice quickly.
- → check LED flashing sequence of left LED's.
- → Count the number of flashes of the blue LED. (* = value 1 | ** = value 2 | etc.).
- → Press button to increase value by one step
- → this is done automatic, the values will be shown 3 times before it jumps to the next Model The "jump" to the next mode is indicated by all 3 LED's flickering twice quickly.
- simply turn off speedo anytime, the most recent values you had choosen will be stored.
- · Table of settings, values and modes: see below (grey-shaded values show "default settings").

DirectAccess Function: For maximum convienence we have incorporated the new DirectAccess function which allows you to jump straight to the mode you would like to change without having to go "the long way" through all the other mode's.

- with speedo turned on, press button and keep pressed (do not release after 3sec!).
- speedo scrolls through the mode's and they are indicated by the LED flashing sequence of the left LED's, blue LED will not flash.
- if you have reached the mode you would like to change (as indicated by left LED's), release button.

The DirectAccess works if you start from the beginning of all mode's, but it also works to jump from Mode.1 straight to Mode.3 for example (simply keep button pressed to activate DirectAccess again!).

MODE.0 (Internal Temp Check System 2): This new feature allows you to accurately check if all is running well or if you're close to shutdown already. The higher the number of flashes, the hotter the speedo ran and every flash equals to 5°C temperature decrease

| Left LED's | #1 | #2 | #3 | #4 | #5 | #6 | #7 | #8 | #9 | #10 |
|------------|--------------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|----------|
| OFF | > -45°C > -81°F | -40°C -72°F | -35°C -63°F | -30°C -54°F | -25°C -45°F | -20°C -36°F | -15°C -27°F | -10°C -18°F | -5°C -9°F | Shutdown |

MODE.1 (AutoCell System): we recommend using value 2 for 4-6 cells NiMH racing purposes, which disengages the LiPo protection. With value #1, the Nexxt 4X automatically detects if a 2S or 3S LiPo is connected and adjusts cut-off accordingly.

| Left LED's | #1 | #2 |
|------------|-----------|--------------|
| Yellow | LiPo/NiMH | 4-6cell NiMH |

MODE.2 (Motor- & Drive Selection): the Nexxt 4X allows you to select from two different drive modes (with or without reverse) and select between brushless and brushed motor operation.

| Left LED's | #1 | #2 | #3 | #4 |
|------------|-----------------------|---------------|-----------------------|---------------|
| Red | Forward/Brake/Reverse | Forward/Brake | Forward/Brake/Reverse | Forward/Brake |
| | Brushless | Brushless | Brushed | Brushed |

MODE.3 (ADPC™ Power Profiles): allows you to adjust the Nexxt 4X to your likes. Either you run on mild or powerful motors or on slippery or high-traction surfaces, we have incorporated a profile for you! Higher value means more overall power and more aggressive throttle response. All settings are available for brushless and brushed motors.

| Left LED's | #1 | #2 | #3 | #4 | #5 | #6 | #7 | #8 |
|---------------------------|---------------------|---------------------|---------------------|---------------------|---------------------|----|--------------------------|----|
| Yellow/Red (alternate) | smooth Power: 1X | smooth Power: 2X | smooth Power: 3X | smooth Power: 4X | linear Power: 4X | | progressive Power: 5X | |

MODE.4 (Automatic Brake): allows you to set a slight braking action which is applied in the neutral range. This enables you to simulate the feel of a brushed motor and also hold the throttle on longer when entering a turn. For brushless motors you achieve the same natural slowdown as a brushed motor with no autobrake when you set value 1-2.

| Left LED's | #0 | #1 | #2 | #3 | #4 | #5 | #6 | #7 | #8 |
|---------------------------|------|--|----|----|----|----|----|----|----|
| Yellow/Red (same time) | none | Going from lowest to highest automatic brake setting (value 1 = minimum / value = maximum) | | | | | | | |

REPAIR PROCEDURES / LIMITED WARRANTY

All products from LRP electronic GmbH (hereinafter called "LRP") are manufactured according to the highest quality standards. LRP guarantees this product to be free from defects in materials or workmanship for 90 days (non-european countris only) from the original date of purchase verified by sales receipt. This limited warranty doesn't cover defects, which are a result of misuse, improper maintenance, outside interference or mechanical damage.

- "This applies among other things on:

 Cut off original power plug or not using reverse polarity protected plugs
 Receiver wire and/or switch wire damaged
 Mechanical damage of the case
 Mechanical damage of electronical components/PCB
 Soldered on the PCB (except on solder posts)
 Connected speed-control with generated polarity."

- Connected speed-control with reversed polarity

To eliminate all other possibilities or improper handling, first check all other components in your model and the trouble shooting guide, if available, before you send in this product for repair. If products are sent in for repair, which do operate perfectly, we have to charge a service fee according to our pricelist.

With sending in this product, the customer has to advise LRP if the product should be repaired in either case. If there is neither a warranty nor guarantee claim, the inspection of the product and the repairs, if necessary, in either case will be charged with a fee at the customers expense according to our price list. A proof of purchase including date of purchase needs to be included. Otherwise, no warranty can be granted. For quick repair- and return service, add your address and detailed description of the malfunction.

If LRP no longer manufactures a returned defective product and we are unable to service it, we shall provide you with a product that has at least the same value from one of the successor series.

The specifications like weight, size and others should be seen as guide values. Due to ongoing technical improvements, which are done in the interest of the product, LRP does not take any responsibility for the accuracy of these specs.

LRP-Distributor-Service:

- · Package your product carefully and include sales receipt and detailed description of malfunction.
- Send parcel to your national LRP distributor.
- Distributor repairs or exchanges the product.
- Shipment back to you usually by COD (cash on delivery), but this is subject to your national LRP distributor's

8. SPECIAL FEATURES

Sensorless Brushless Design: Revolutionary LRP software providing sensored driveability even without

ADPC™ Power Profiles: Advanced Digital Phase Control results in more power and better driveability. Depending on the status of the car (start, acceleration, full speed) the software calculates the perfect motor management by adjusting current limiter, motor timing, throttle curve and more! Higher value means more overall power and aggressive response.

D.E.M.S. Brushed - Power Profiles: The known and world's winning D.E.M.S. Brushed Quantum style power programs have been implemented into the *LRP Nexxt 4X* aswell. Higher value means more overall power and aggressive response.

Internal-Temp-Check System 2: the Nexxt 4X allows you to read-out the maximum internal temperature that the speedo reached. To store it to the memory, briefly apply brakes after the run before you turn the switch off. You can convienently read-out the temperature back in the pits since it remains stored until you turn it on the next time regularly (which will reset the memory). This new feature allows you to accurately check if all is running well or if you're close to shutdown already. The higher the number of flashes, the hotter the speedo ran. Thermal shutdown would occur at 10 flashes

DirectAccess Function: For maximum convienence we have incorporated a quick DirectAccess function which allows you to jump straight to the mode you would like to change without having to go "the long way" through all the other mode's.

See section 7 "Mode Programming" on how to use the DirectAccess function.

 $\label{eq:barker} \textit{Brake Adjustment:} \ A \ good \ starting \ point for the brake setting on your radio is 80\% for all classes. Make sure you do the radio-setup with all settings on the radio on 100%!$

AutoCell System: Ready for the next battery technology — LiPo batteries! LRP's exclusive and smart Auto-Cell System ensures that LiPo batteries can be used safely without accidentially deep-discharging of the cells. Motor power will be reduced (no shutdown will occur!) if the system recognises very low battery voltage. It is self adjusting to 2S or 3S LiPo batteries!

Waterproof: Due to latest production technologies and use of HighTech materials, it was possible to make these speed-controls fully waterproof! This material also makes the speed-controls more shock resistant then other similar products. It's no longer needed to seal your speed-control when you are driving in the rain/snow! But please make sure you still seal your other electronic components (receiver, servo and motor) since these are normally not waterproof and will get damaged due to the water.

Changing Mode settings without the transmitter: At race events you usually do not have access to your transmitter, but never mind since you can simply disconnect the receiver lead from the receiver and change the MODE settings as described in section 7 "Mode Programming".

Power Capacitor: Never disconnect the power-capacitor! It offers increased punch and additional protection, it must be connected to BAT+ and BAT- solder posts with shortest possible wires.

IceDrive Design: LRP's secret IceDrive Design results in lower speedo temperature under all racing conditions and for both brushless + brushed. Sorry, no further details to be disclosed. Simply a step ahead of the

Fail Safe System: Digital protection against radio interference, "The guardian angel". The safety electronic can detect reception of a "false" or incomplete radio signal, e.g due to a low transmitter battery or environmental radio interference which reach the model, or if the model is out of the transmitter range. For protection against damage, the speed-control switches to the neutral position, and the model comes to a stop.

Multi-Protection System, 3-way protection: The perfect protection against short-circuits (motor), overload and overheating. If your speed-control faces overload, the motor function will be shut-off for protection and the blue LED will flash, although the steering function is maintained. Let the speed-control cool down for a few minutes. If you experience frequent shutdowns, check for the following

- Correct gear ratio (refer to motor manual for gearing recommendations)
 ADPC setting too high (higher value will heat up motor and speed-control excessively)
- Motor is too strong or motor is damaged.

9. TROUBLESHOOTING GUIDE

| SYMPTOM | CAUSE | REMEDY | |
|---|---|--|--|
| Servo is working, no motor function. | Speed-control plugged in incorrectly | Plug speed-control in Ch 2 | |
| 3, | Overload protection activated | Allow speed-control to cool down | |
| | Wiring problem | Check wires and connectors | |
| | Motor defective | Replace motor | |
| | Speed-control defective | Send in product for repair | |
| No servo and no motor function. | Speedo connected to receiver with wrong polarity | Connect speedo with correct polarity | |
| | RX-/Switch Harness not plugged in correctly | Connect RX-/Switch-Harness correctly | |
| | Battery defective | Replace with different battery pack | |
| | Crystal defective | Replace components one by one. | |
| | Receiver defective | 1 | |
| | Transmitter defective | 1 | |
| | Speed-control defective | Send in product for repair | |
| Motor stutters while accelerating | Power Capacitor damaged | replace Power Capacitor | |
| · · | Radio Interference | Change location of components | |
| | Motor defective | Replace motor | |
| | Speed-control defective | Send in product for repair | |
| Motor runs in reverse when accelerating forward on the transmitter. | Motor connected for reverse operation | Swop two of the 3 phase wires | |
| | BM - Motor connected with reversed polarity | Connect motor correctly | |
| | Transmitter settings changed after set-up | Repeat set-up procedure | |
| Insufficient performance. | Motor pinion too big or gear ratio too long. | Use smaller motor pinion/shorter gear ratio | |
| E.g. poor brake power, topspeed or acceleration. | Transmitter settings changed after set-up | Repeat set-up procedure | |
| acceleration | Power Capacitor damaged | Replace Power Capacitor | |
| | BM - Motor worn out | Maintain motor | |
| | Motor defective | Replace motor | |
| | Speed-control defective. | Send in product for repair | |
| Speed-control switches off | Model used too often without cool-down periods | Let speed-control cool down after every run | |
| frequently. | Motor stronger than motorlimit or input voltage too high | Use only motors and batteries which are within the specifications of the speed-control | |
| | Motor pinion too big (e.g. gear ratio too long) | Use smaller motor pinion/shorter gear ratio | |
| | Stuck drivetrain or ballbearing | Maintain model | |
| | Motor defective | Replace motor | |
| Motor never stops, runs at constant slow speed | Transmitter settings changed after set-up | Repeat set-up procedure | |
| Radio interference | Receiver or antenna too close to power wires, motor, battery or speed-control. Receiver aerial too short or coiled up | See "Installation Tips" and "Installation" | |
| | Receiver defective, too sensitive; Transmitter defective, transmitter output power too low, servo problem | Replace components one by one Only use original manufacturers crystals | |
| | Poor battery connection | Check plugs and connecting wires | |
| | Transmitter batteries empty | Replace / recharge transmitter batteries | |